



Tidal Flow: A Fast and Teachable Maximum Flow Algorithm

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Algorithms **Live!**

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Maximum Flow Problems in CP

- Problems are interesting
- High variation of problem ideas (vs spanning tree algorithms, shortest paths, etc)
- Harder problems require faster algorithms



Timeline for Tidal Flow

2012		ACM ICPC WF (invented)
2013	}	Taught at U Central Florida
...		
2016		
2017		IOI Conference suggested
2018		Present



Algorithms in Competitive Programming

- Easy to teach
- Easy to implement
- Efficient in practice



Example: Fenwick Tree

```
void update(int i, int delta) {  
    while (i < size) {  
        table[i] += delta;  
        i += i&-i;  
    }  
}
```

```
void sum(int i) {  
    int sum = 0;  
    while (i > 0) {  
        sum += table[i];  
        i -= i&-i;  
    }  
    return sum;  
}
```

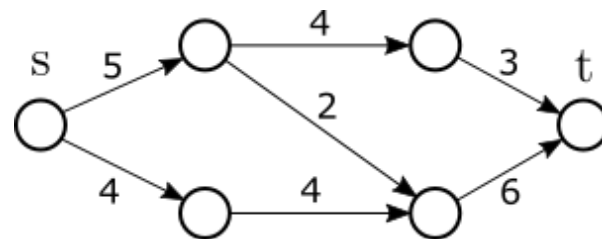


Overview

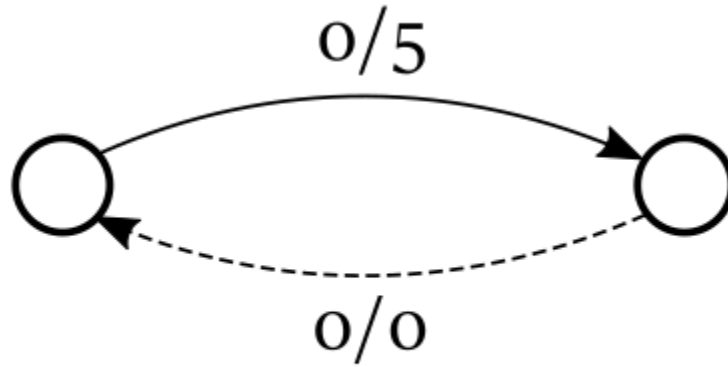
- Review of the maximum flow problem and blocking flows
- Tidal Flow
- Theoretical performance
- Empirical performance
- Open questions

Maximum Flow

- Input: (G, s, t, cap)
 - $G = (V, E)$
 - $s, t \in V$
 - $cap: E \rightarrow \mathbb{R}^+$
- Output: $f: E \rightarrow \mathbb{R}^*$
- Constraints:
 - Capacity Constraint: $f(e) \leq cap(e)$ for all $e \in E$
 - Conservation Constraint: $\sum f(w, v) = \sum f(v, u)$ for all $v \in V \setminus \{s, t\}$
- Maximize: $\sum f(s, v)$ for all $v \in V$

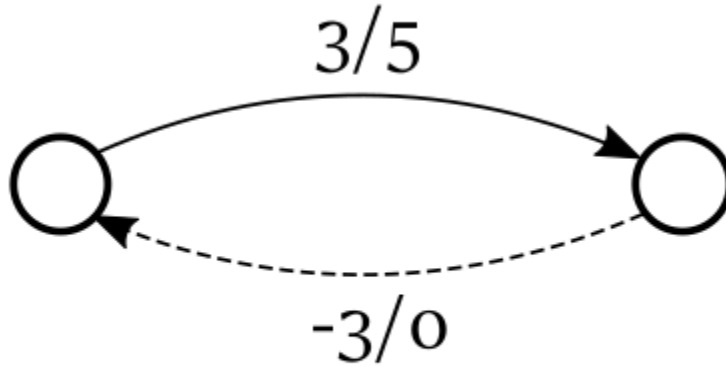


Maximum Flow: Reverse Edges



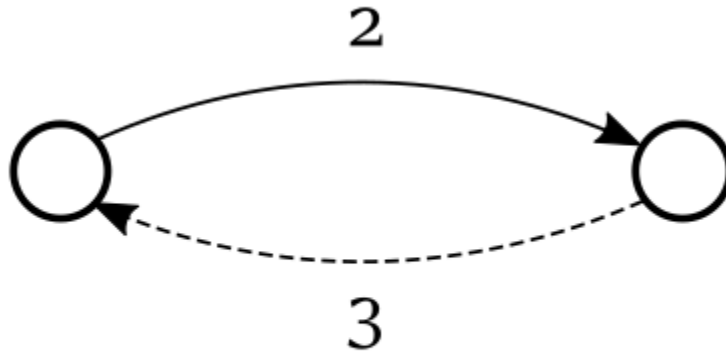
flow/cap

Maximum Flow: Reverse Edges



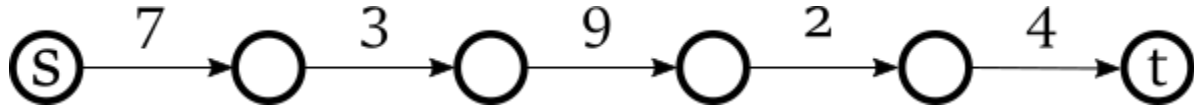
$$f(w, v) = -f(v, w) \text{ for all } (w, v) \in E$$

Maximum Flow: Residual Capacities

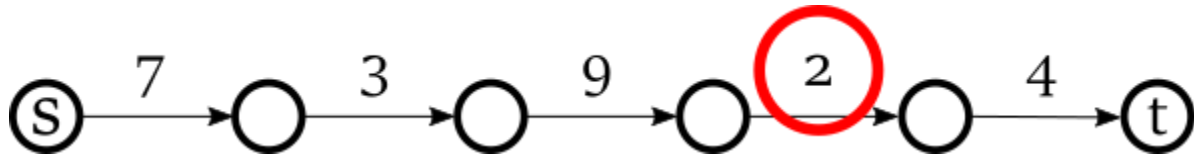


$$cap_r(w, v) = cap(w, v) - f(w, v) \text{ for all } (w, v) \in E$$

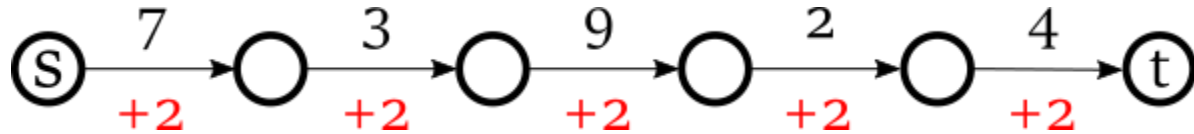
Augmenting Paths



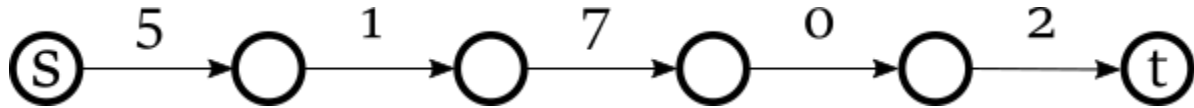
Augmenting Paths



Augmenting Paths



Augmenting Paths

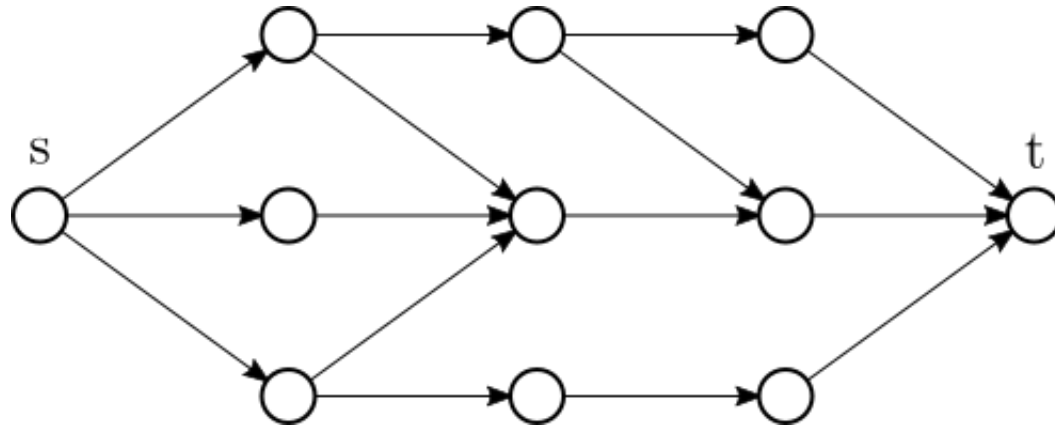




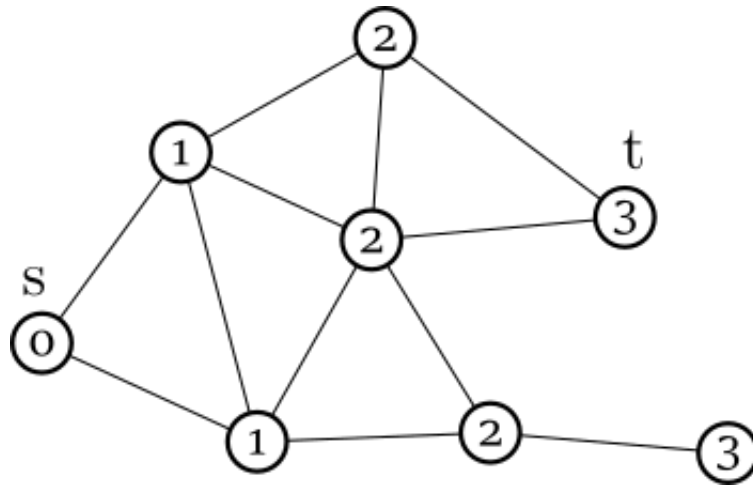
Augmenting Paths: Runtime

- Arbitrary Paths: $O(fm)$
- Shortest Paths: $O(nm^2)$

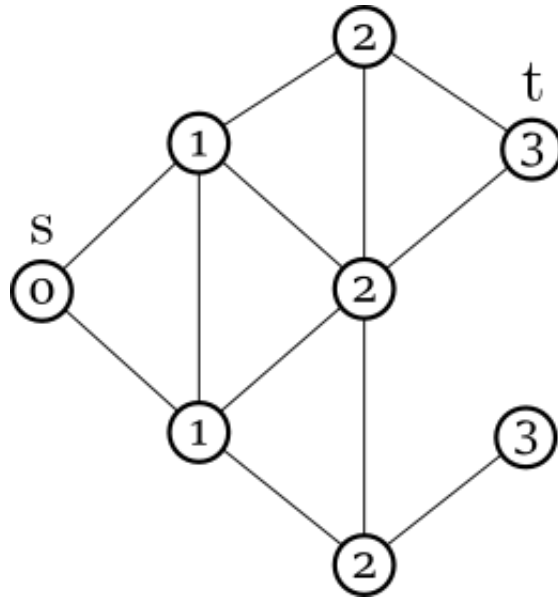
Dinitz Algorithm



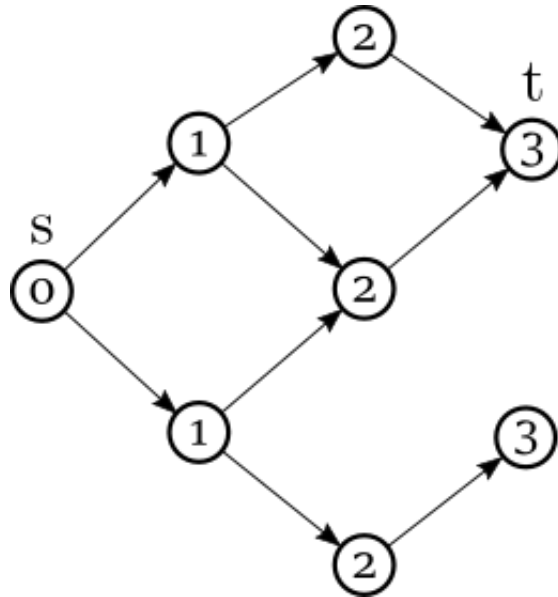
Level Graph



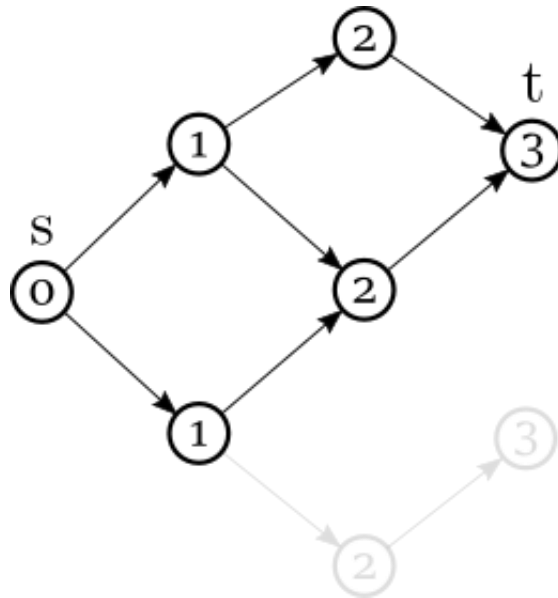
Level Graph



Level Graph



Level Graph





Dinitz

- Blocking flows discovered in $O(nm)$ through modified DFS
- At most $O(n)$ level graphs possible
- Runtime: $O(n^2m)$



Tidal Flow

- Same goal as Dinitz: block the level graph
- Try blocking in $O(m)$ runtime
- Failure is OK! Keep trying.



Tidal Flow: Conceptual Metaphor

“A (conceptual) metaphor is a cognitive process that occurs when a subject seeks understanding of one idea (the target domain) in terms of a different, already known idea (the source domain). The subject creates a conceptual mapping between the properties of the source and the target, thereby gaining new understanding about the target.” (Forišek and Stienová, 2013)

Here the metaphor is oceanic tides.



Tide Cycle

- High Tide
- Low Tide
- Erosion



Tide Phase: High Tide

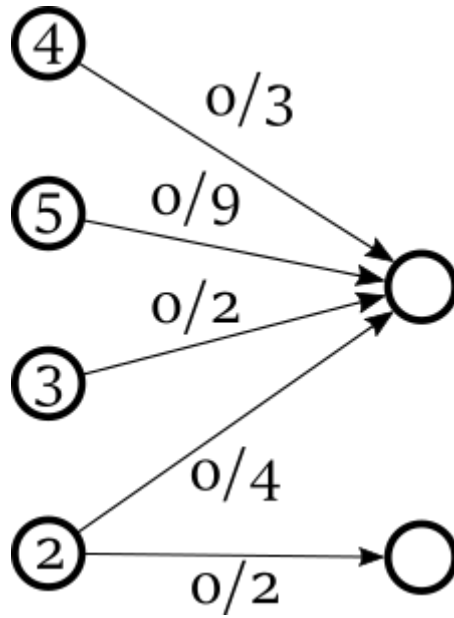
- For each vertex, compute $h: V \rightarrow R^*$

$$h(v) = \sum_{w \in G(v)} \min(\text{cap}(w, v) - f(w, v), h(w))$$

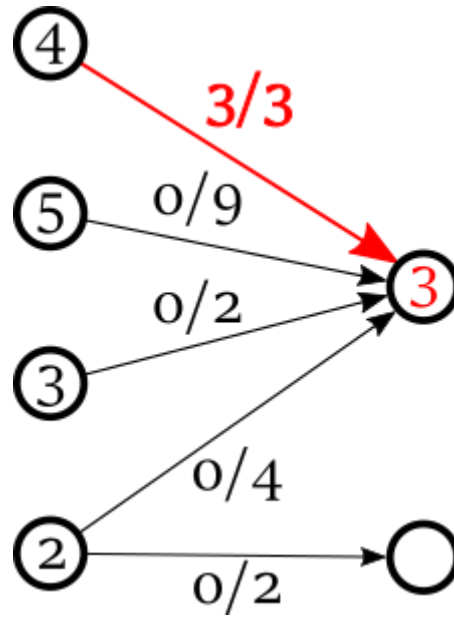
- Store promised flow $p: E \rightarrow R^*$

$$p(w, v) = \min(\text{cap}(w, v) - f(w, v), h(w))$$

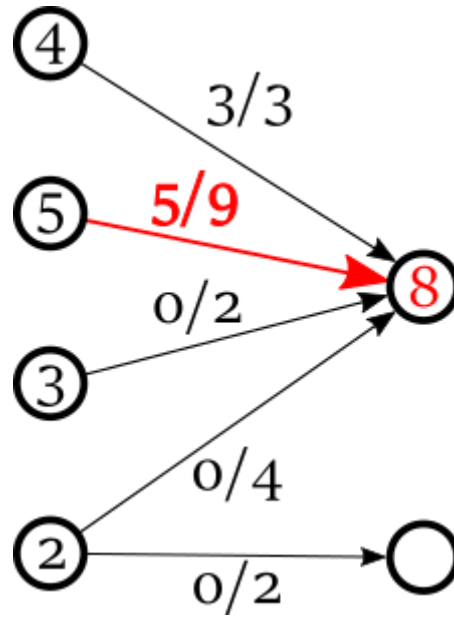
High Tide



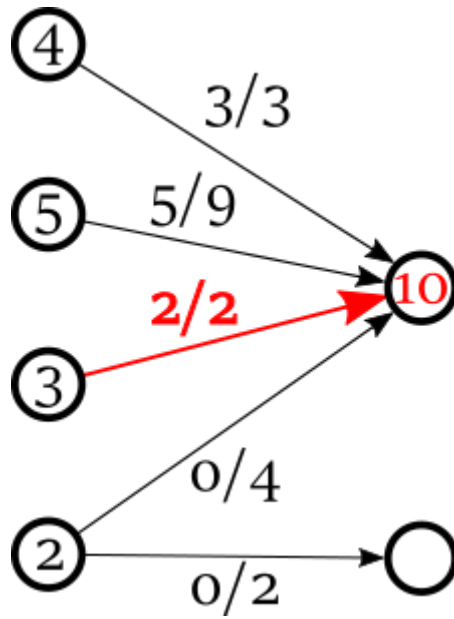
High Tide



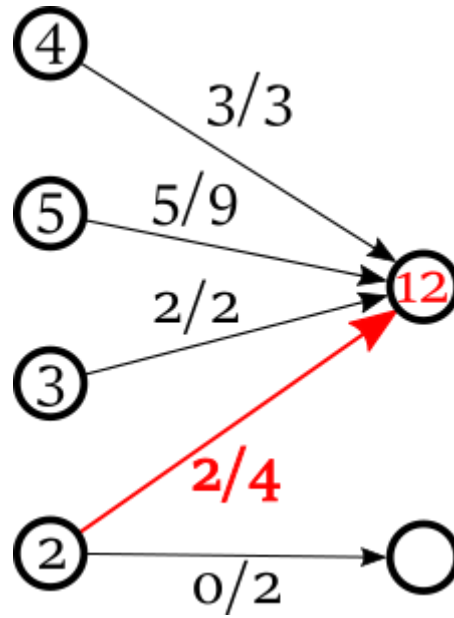
High Tide



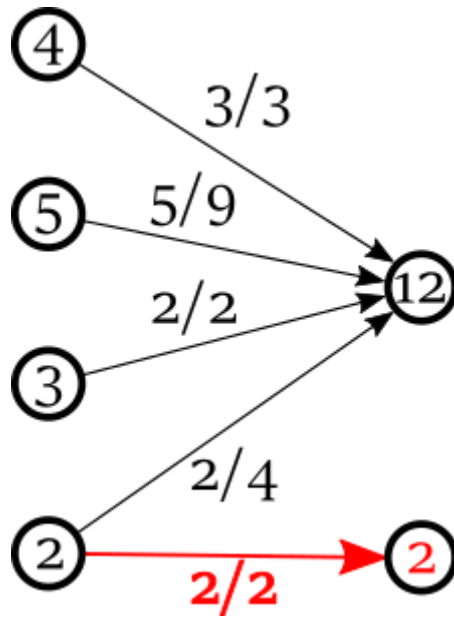
High Tide



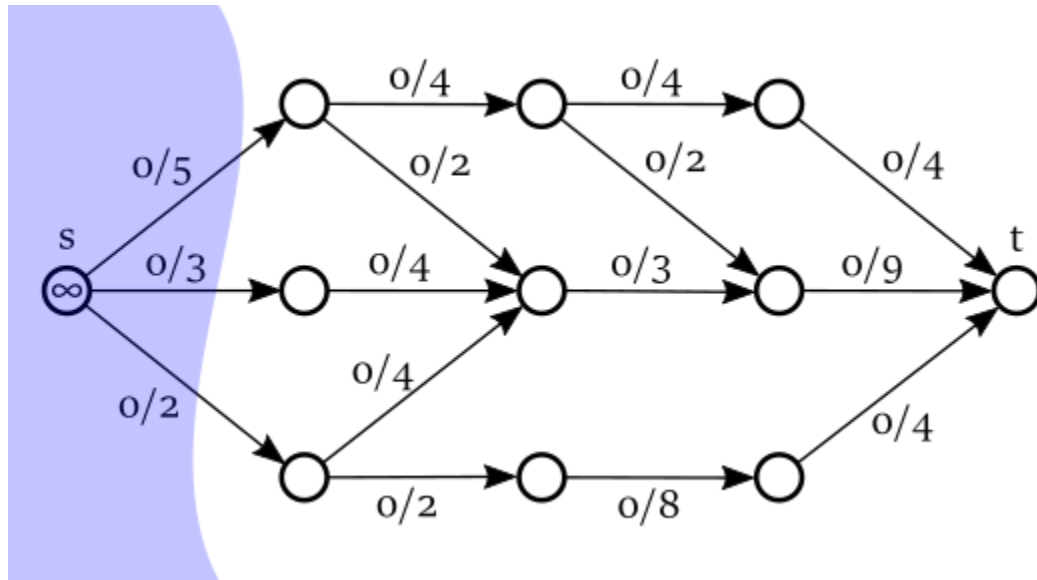
High Tide



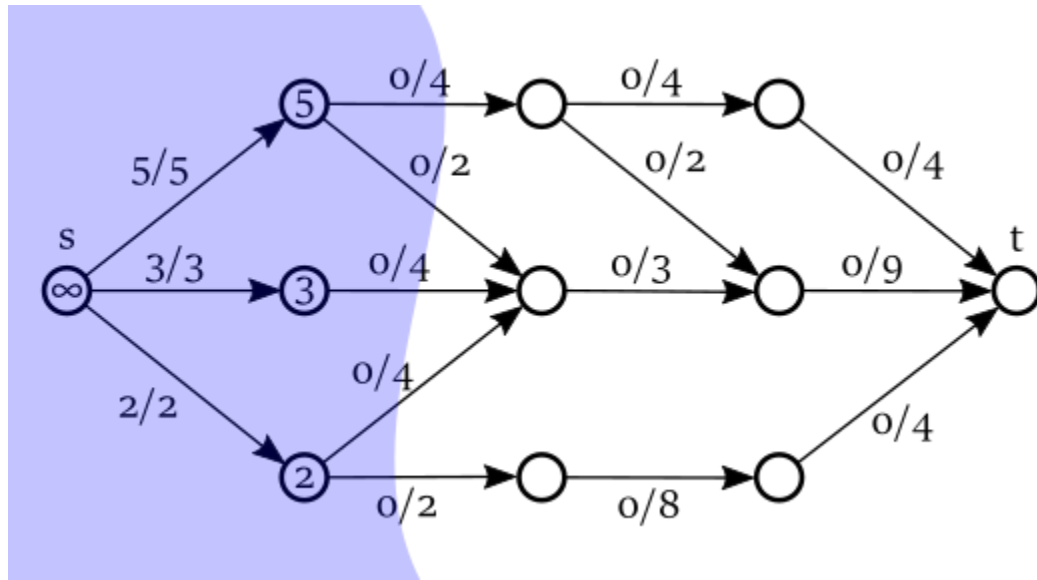
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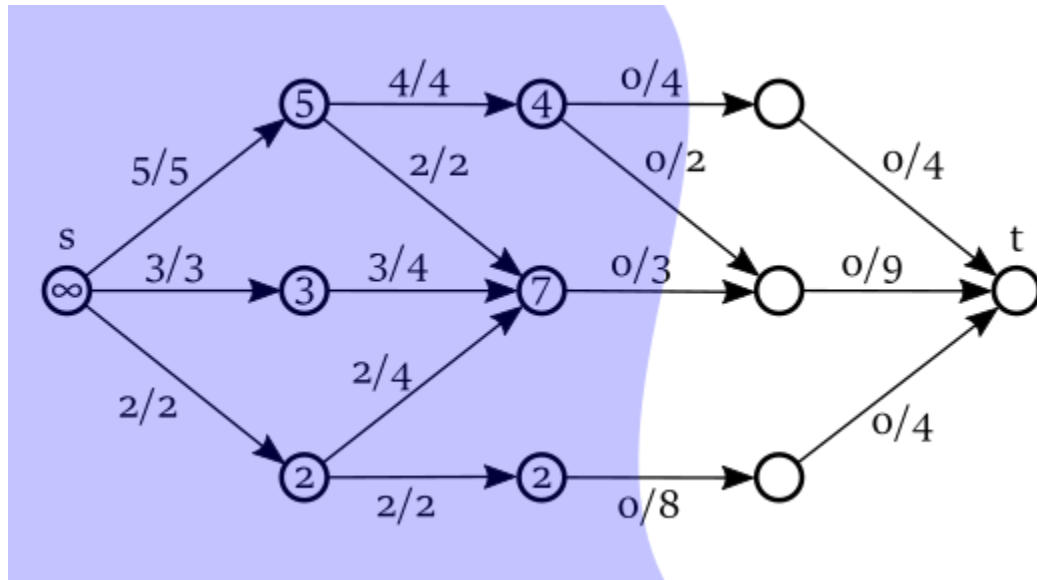
High Tide



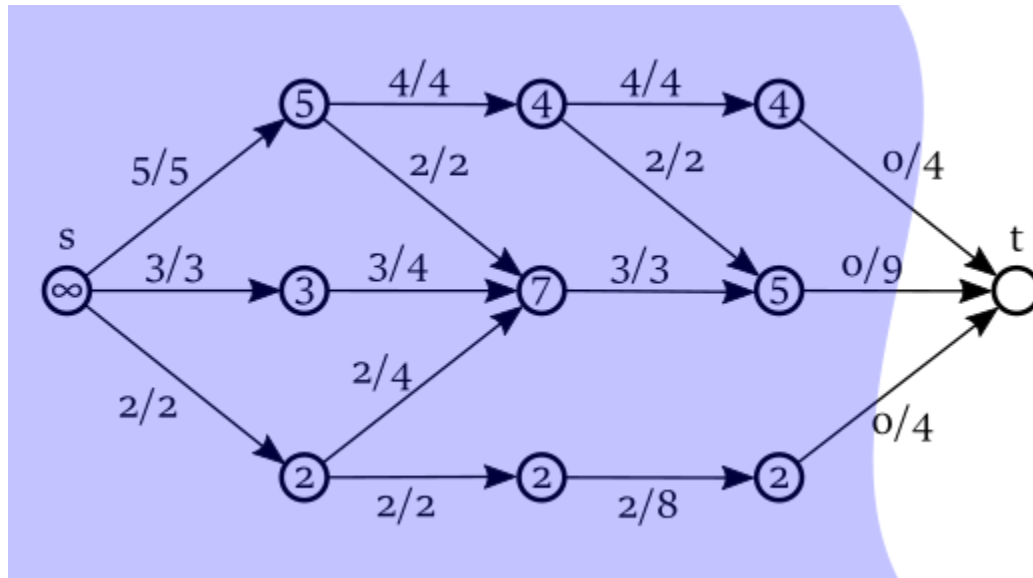
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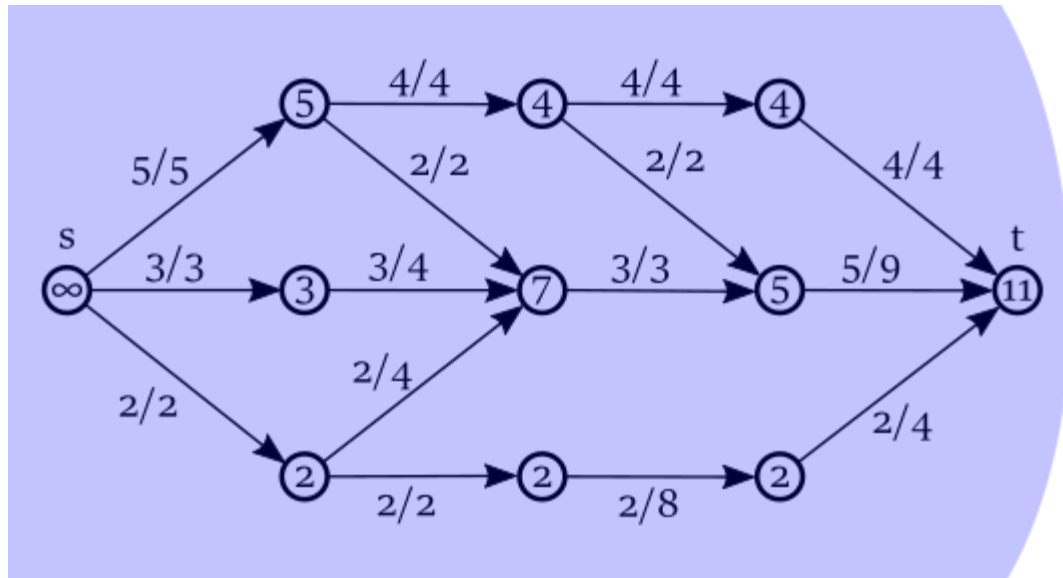
High Tide



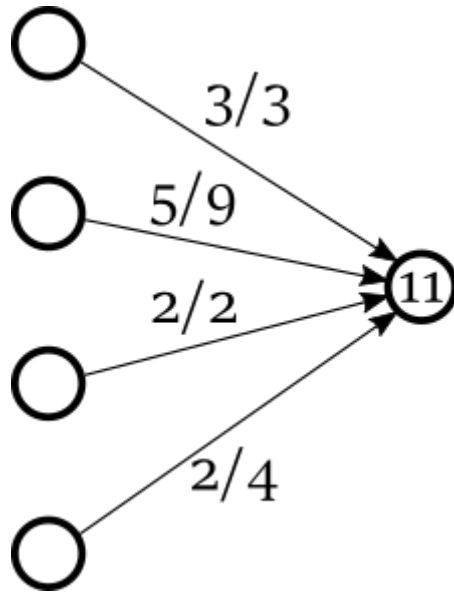
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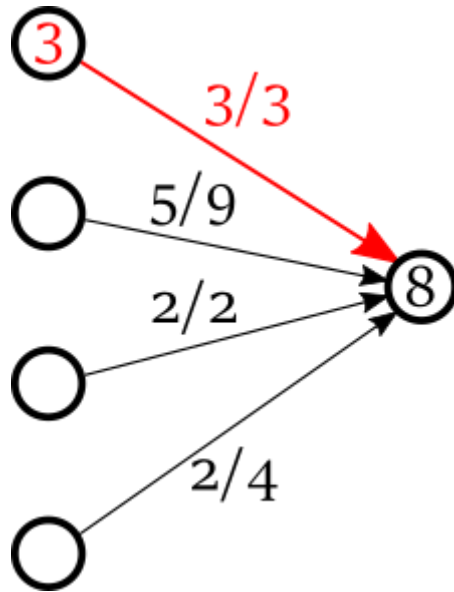
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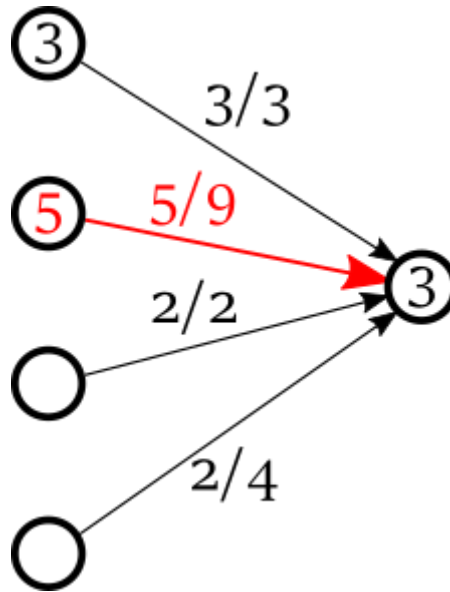
Low Tide



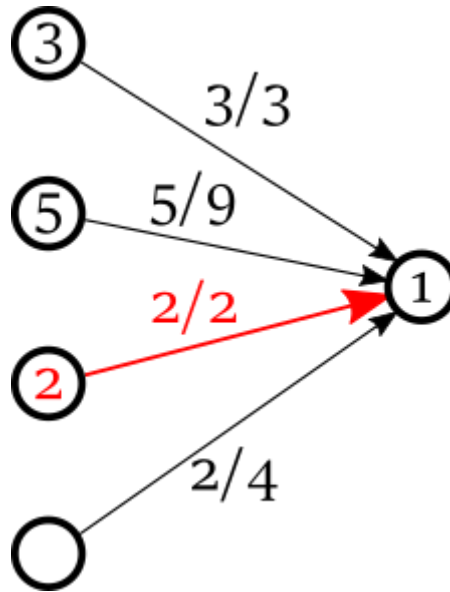
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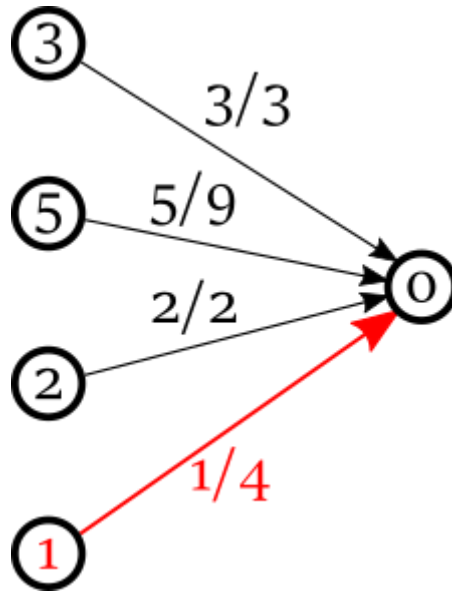
Low Tide



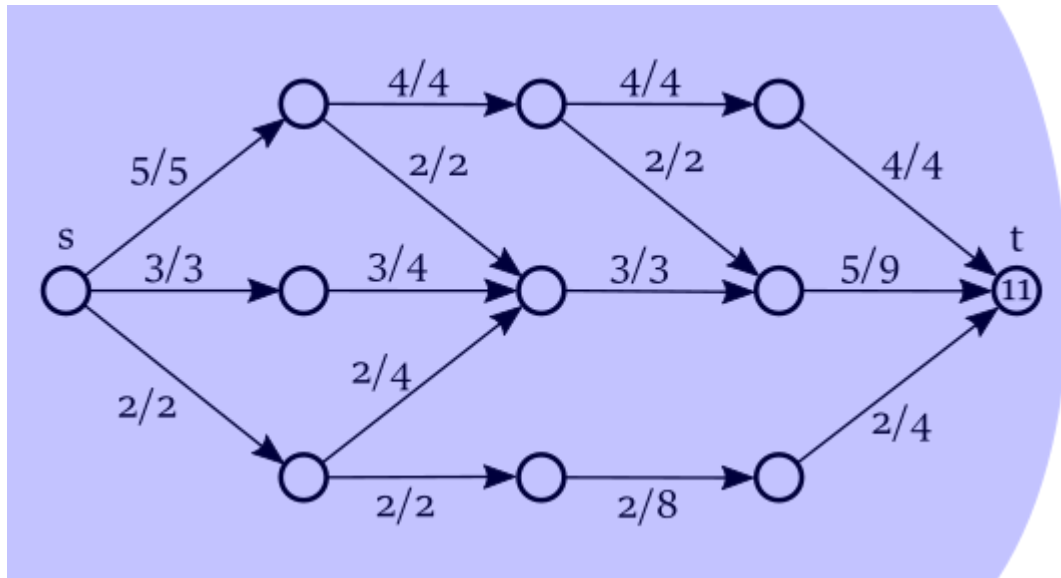
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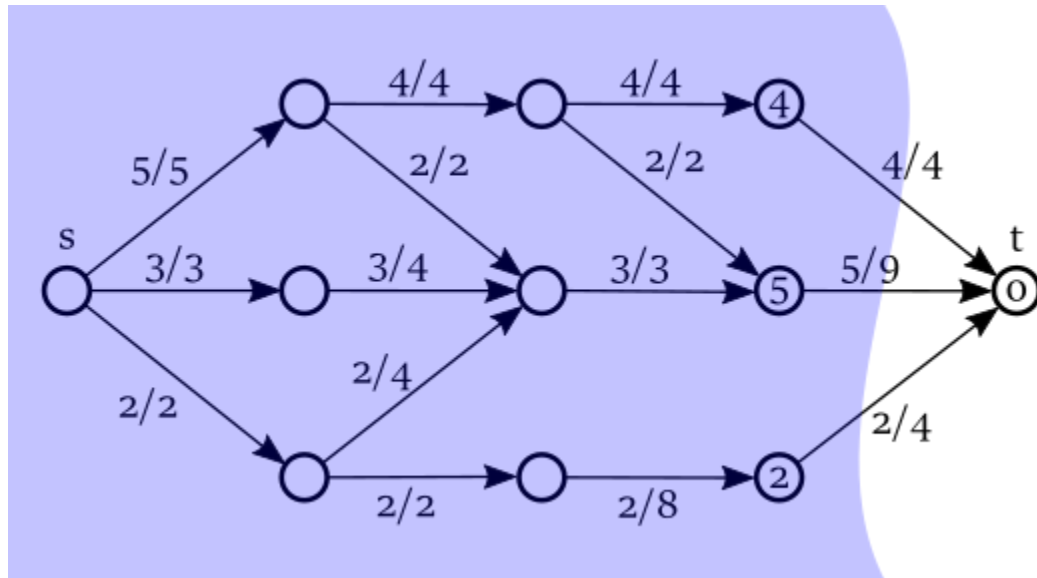
Low Tide



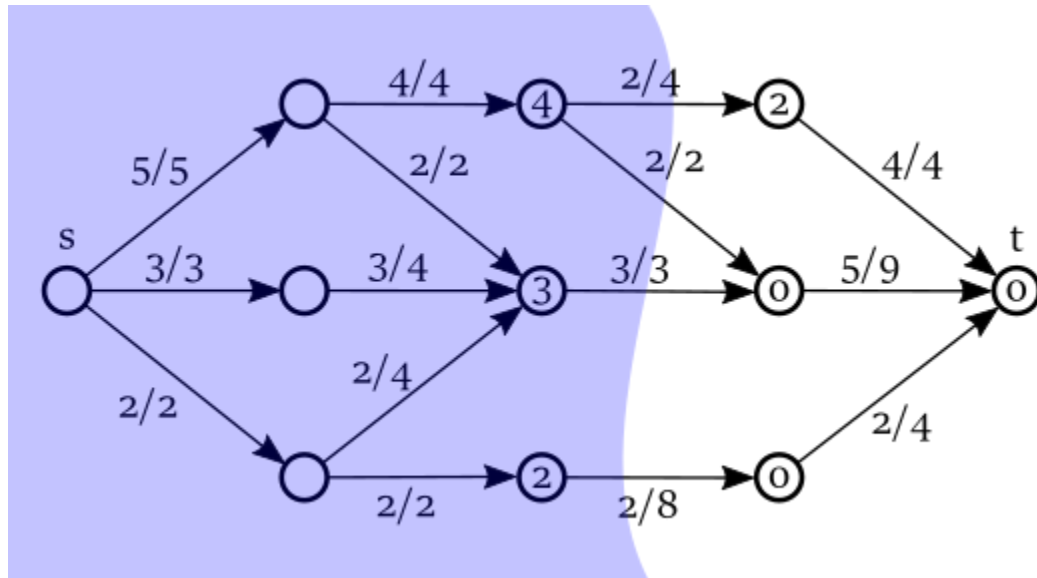
Low Tide



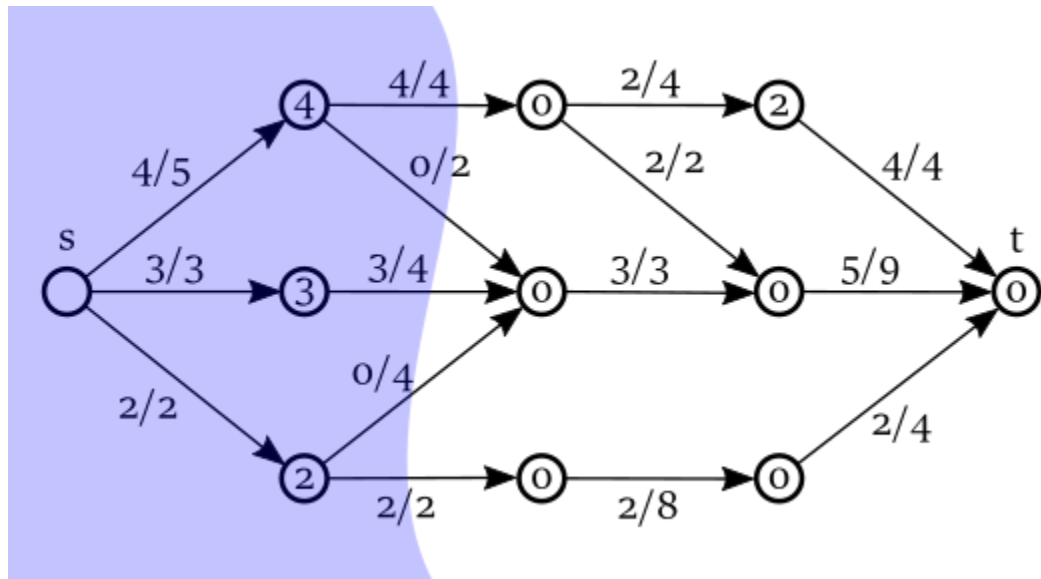
Low Tide



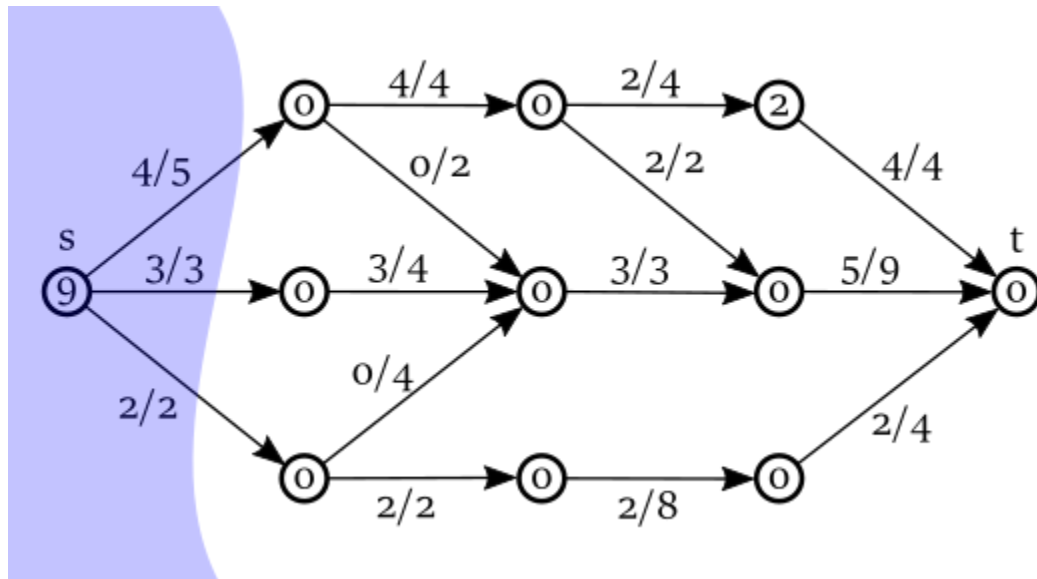
Low Tide



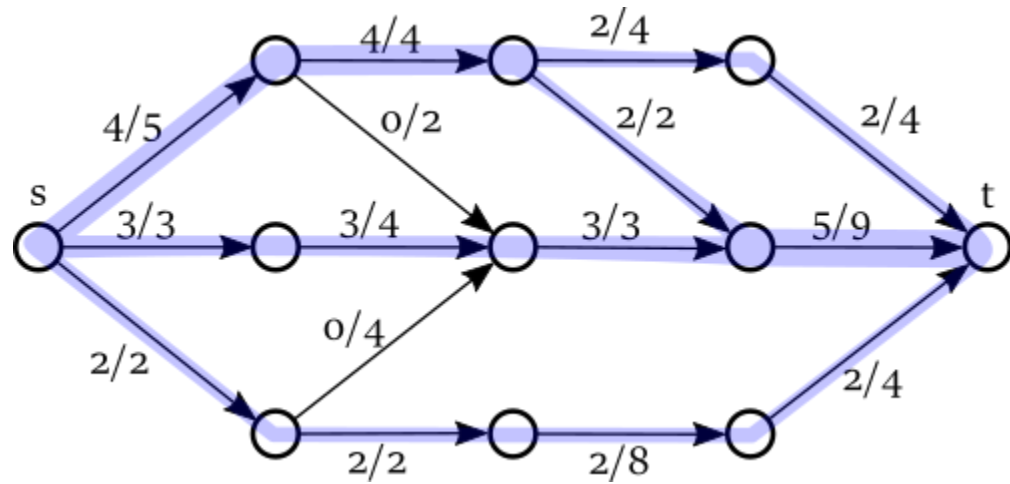
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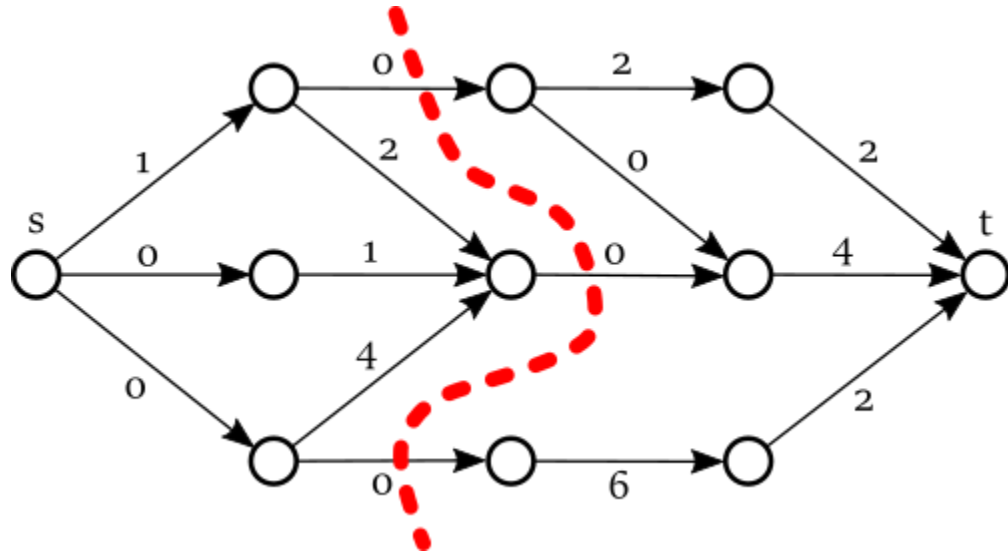
Low Tide



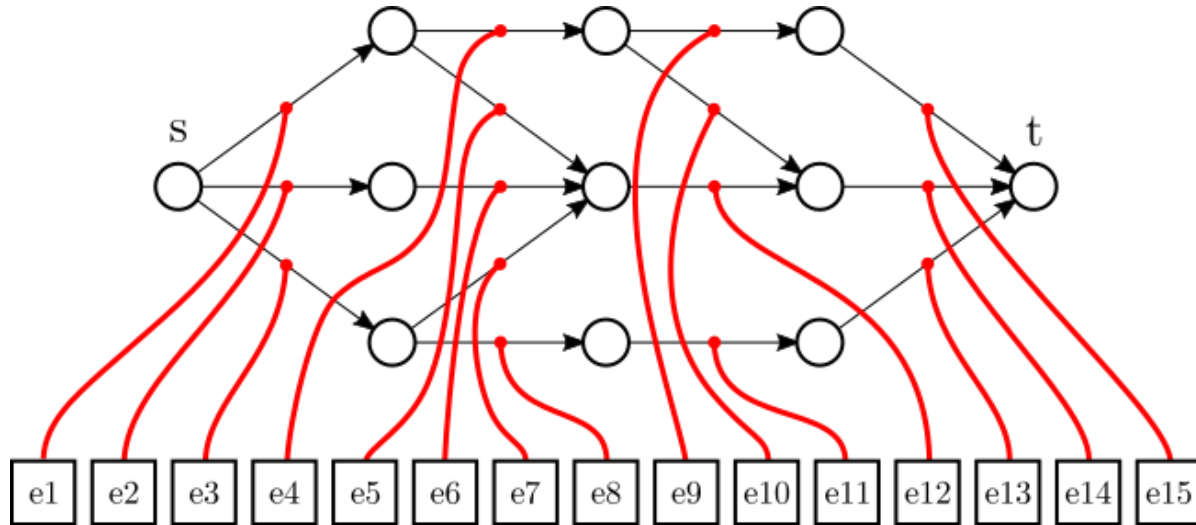
Erosion



Erosion



Implementation





Implementation: High Tide

```
 $h(v) = 0$  for all  $v \in V$ ;  
 $h(source) \leftarrow \infty$ ;  
foreach edge  $e_i(w, v) \in E$  do  
     $p(e_i) \leftarrow \min(cap(e_i) - f(e_i), h(w))$ ;  
     $h(v) \leftarrow h(v) + p(e_i)$ ;  
end
```



Implementation: Low Tide

```
 $l(v) = 0$  for all  $v \in V$   
 $l(sink) \leftarrow h(sink);$   
foreach edge  $e_i(w, v) \in E$  in reverse order do  
     $p(e_i) \leftarrow \min(p(e_i), h(w) - l(w), l(v));$   
     $l(v) \leftarrow l(v) - p(e_i);$   
     $l(w) \leftarrow l(w) + p(e_i);$   
end
```



Implementation: Erosion

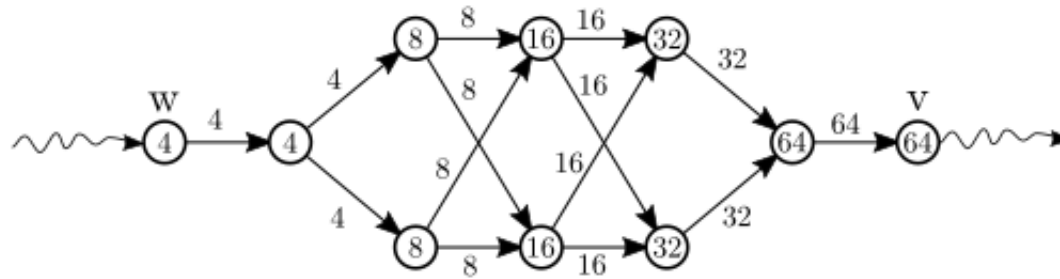
```
 $h(v) = 0$  for all  $v \in V$ ;  
 $h(\text{source}) \leftarrow l(\text{source})$ ;  
foreach edge  $e_i(w, v) \in E$  do  
     $p(e_i) \leftarrow \min(p(e_i), h(w))$ ;  
     $h(w) \leftarrow h(w) - p(e_i)$ ;  
     $h(v) \leftarrow h(v) + p(e_i)$ ;  
     $f(e_i) \leftarrow f(e_i) + p(e_i)$ ;  
     $f(\text{rev}(e_i)) \leftarrow f(\text{rev}(e_i)) - p(e_i)$ ;  
end
```



Run-time Analysis

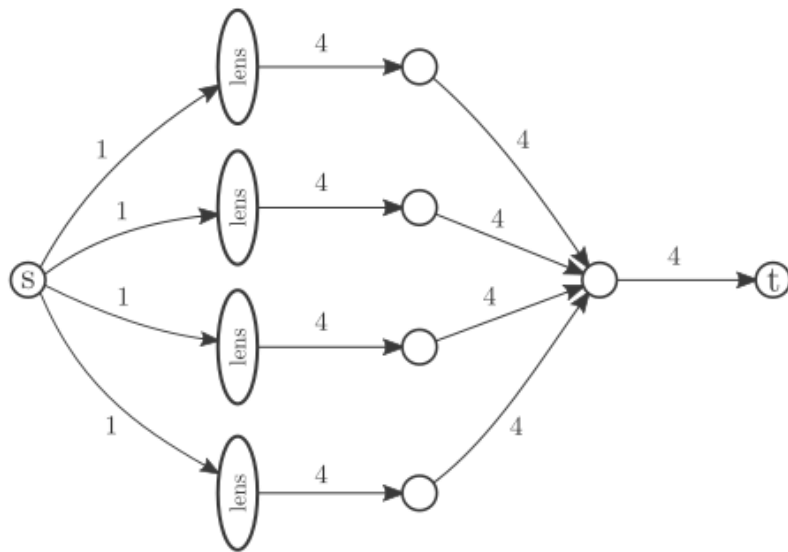
- Shortest Augmenting Path: $O(nm^2)$

Bounding Tide Cycles



Bounding Tide Cycles

Requires $O\left(\frac{n}{\log(n)}\right)$ tide cycles.

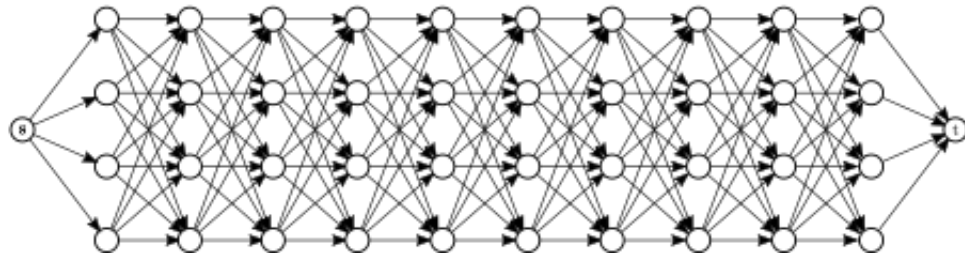
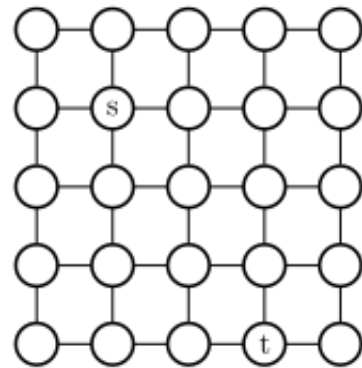
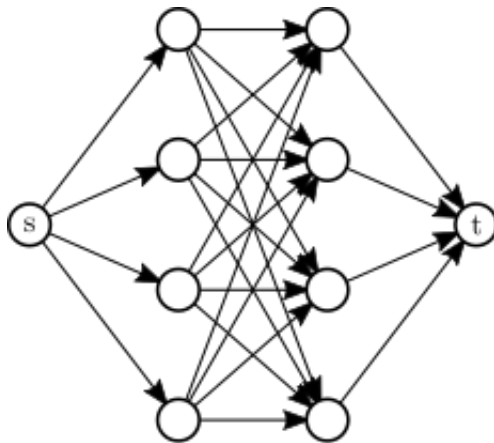




Experiments

- Six suites of tests
- 200 tests per suite (10 different values of n)
- Experiments run against five other algorithms
- Also included a version of Tidal Flow without heuristic function h
- Each algorithm run for a maximum of 20 seconds

Test Suites





Bipartite Matching Suites

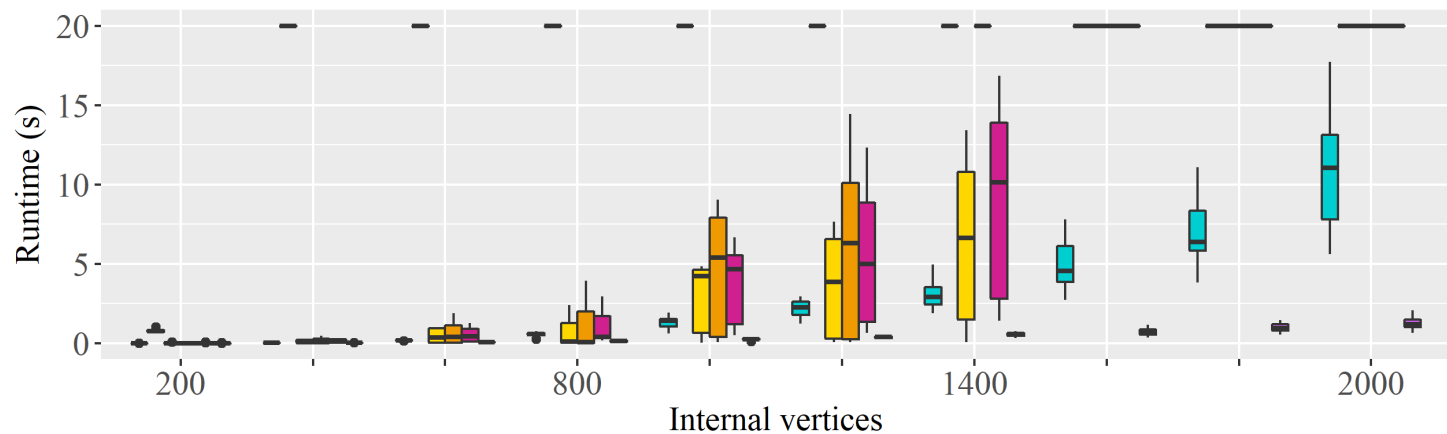
- Sparse versus dense
- Unit versus high capacity



Flow Algorithms

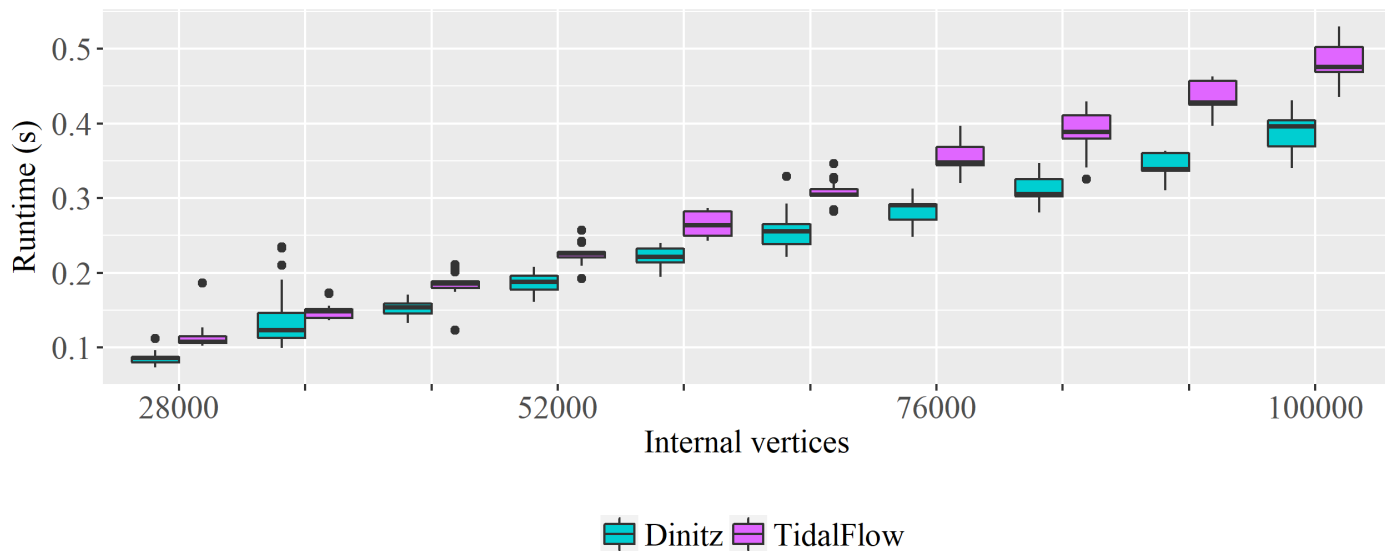
- Shortest Augmenting Path (Edmonds and Karp, 1972)
- Dinitz Algorithm (Dinitz, 1970)
- Preflow-Push (Goldberg and Tarjan, 1988)
- Preflow-Push with Gap Heuristic (Goldberg and Tarjan, 1988)
- Improved Shortest Augmenting Path (Orlin and Ahuja, 1987)

Results: Dense High Capacity BPM



Dinitz ISAP PreflowPush
Edmonds-Karp PreflowPush(Gap) TidalFlow

Results: Sparse Unit BPM





Open Questions

- Empirical study is only preliminary
- Bounding tide cycles: $O\left(\frac{n}{\log(n)}\right)$ versus $O(m)$
- Empirical results suggest $O(nm^2)$ runtime is not tight
- Does a better h exist?

Questions?